catkin\_init\_workspace 初始化workspace,生成一个CMakeLists.txt (在src下输入这个命令)

catkin\_make 回到上级目录，对该目录进行编译

source devel/setup.bash 对目标空间进行source

roscore 启动ros系统自带的节点

rviz

open config – src/grid\_path\_searcher/launch/rviz\_confi/demo.rviz

roslaunch grid\_path\_searcher demo.launch